

ARTESYN NDQ900-48S12B

900 Watts Non-Isolated Quarter-brick Converter

PRODUCT DESCRIPTION

Advanced Energy's Artesyn NDQ900-48S12B-6LI is a new generation non-isolated single output digital control DC/DC converter with standard quarter-brick outline and pin configuration, as well as PMBusTM option. It delivers up to 900 W with 12.25 V output voltage. Ultra high peak efficiency of 96.7% and excellent thermal performance makes it an ideal choice for 48 V to 12 V down conversion in high power computing and storage applications. It can produce full power over an operating temperature range of -40°C to +85°C with forced air cooling. PMBusTM interface is also provided for flexible digital control and monitoring.

SPECIAL FEATURES

- Delivering up to 900 W
- Ultra-high efficiency 96.7% peak
- Wide input range: 40 to 60 Vdc
- PMBusTM function
- Excellent thermal performance
- Parallel operation, active current sharing
- Power good function
- No minimum load requirement
- Fixed switching frequency
- Baseplate for contact cooling
- RoHS 3.0
- Remote control function
- Input undervoltage lockout
- Input overvoltage lockout
- Output overcurrent protection
- Output overvoltage protection
- Over temperature protection
- Pin length option: 3.8 mm

SAFETY

- IEC/EN/UL/CSA 62368-1
- CE
- UL/TUV
- UL94 V-0

TYPICAL APPLICATIONS

- Telecom
- Datacom
- Computing and storage



AT A GLANCE

Total Power

900 Watts

Input Voltage

40 to 60 Vdc

of Outputs

Single





NDQ900-48S12B

MODEL NUMBERS

| Part number | Output Voltage | Structure | Pin Type | RoHS Status | PMBus™ |
|-------------------|----------------|-----------|--------------|-------------|--------|
| NDQ900-48S12B-6LI | 12.25 Vdc | Baseplate | Through hole | RoHS 3.0 | Yes |

Order Information

| NDQ900 | - | 48 | S | 12 | | В | - | 6 | L | I | Н | |
|--------|---|----|---|-----|---|---|---|------------|---|---|----|-----|
| 1 | | 2 | 3 | (4) | 5 | 6 | | \bigcirc | 8 | 9 | 10 | (1) |

| 1) | Model series | NDQ: high efficiency non-isolated digital control quarter brick series 900: output power 900 W |
|------|-----------------------------------|---|
| 2 | Input voltage | 48: 40 to 60 V input range, rated input voltage 50 V |
| 3 | Output number | S: single output |
| (4) | Rated output voltage | 12: 12.25 V output |
| 5 | Enable polarity | Blank: negative logic; P: positive enable |
| 6 | Baseplate status | B: with baseplate |
| 7 | Pin length | -6: 3.8 mm, -4: 4.8 mm |
| 8 | RoHS status | L: RoHS 3.0 |
| 9 | PMBus [™] interface pins | I: I-share pin, PMBus pins and PG-pin; Blank: no I-share pin, PMBus pins or PG-pin. |
| (10) | Power pin config | Blank: single pair of power pins; H: double pair of power pins |
| (11) | Customization code | TBD |

Options

None



Absolute Maximum Ratings

Stress in excess of those listed in the "Absolute Maximum Ratings" may cause permanent damage to the power supply. These are stress ratings only and functional operation of the unit is not implied at these or any other conditions above those given in the operational sections of this TRN. Exposure to any absolute maximum rated condition for extended periods may adversely affect the power supply's reliability.

| Table 1. Absolute Maximum Ratings | | | | | | |
|--|-------|--------------------|----------|-----|----------|------------|
| Parameter | Model | Symbol | Min | Тур | Max | Unit |
| Input Voltage Operating - Continuous Non-operating 100ms | All | V _{IN,DC} | 40 40 | - | 60 80 | Vdc Vdc |
| Maximum Output Power ¹ | All | P _{O,max} | - | - | 900 | W |
| Ambient Operating Temperature | All | T _A | -40 | - | +85 | °C |
| Storage Temperature | All | T _{STG} | -55 | - | +125 | °C |
| Humidity (non-condensing) Operating Non-operating | All | | - | - | 95 95 | % % |

Note 1 – 1000 W / 50 ms peak power. When peak power occurs, the average power with peak power will not exceed 900 W.



Input Specifications

| Table 2. Input Specifications (Tested with the Application Circuit as Figure 12) | | | | | | | |
|--|----------------------------|--|-------------------------|-----|--------------|------|--------|
| Parameter | | Conditions ¹ | Symbol | Min | Тур | Max | Unit |
| Operating Input Voltage, DC | | All | V _{IN,DC} | 40 | 50 | 60 | Vdc |
| | Turn-on Voltage Threshold | All | V _{IN,ON} | 35 | - | 40 | Vdc |
| Input Under Voltage Lockout | Turn-off Voltage Threshold | All | V _{IN,OFF} | 34 | - | 39 | Vdc |
| 0 | Lockout Voltage Hysteresis | All | | 1 | - | 3.5 | Vdc |
| Input Overvoltage | Protection | All | | 61 | - | 68 | Vdc |
| Maximum Input Current | | $V_{IN,DC} = 40 \text{ Vdc},$ $I_O = I_{O,max}$ | l _{IN,max} | - | - | 24.3 | А |
| No Load Input Current | | All | I _{IN,no_load} | - | 0.18 | - | А |
| Standby Input current | | Remote OFF | I _{IN,standby} | - | 0.02 | - | А |
| Recommended Input Fuse | | Fast blow external fuse is recommended | | - | - | 50 | А |
| Input Reflected Ripple Current (RMS) ² | | Through 12 uH inductor | | - | 50 | - | mA |
| Recommended External Input Capacitance | | Low ESR capacitor is recommended | C _{IN} | 300 | - | - | uF |
| Operating Efficiency | | | η | - | 96.4 96.7 | - | % % |

Note 1 - $T_A = 25^{\circ}$ C, Vin = 50 Vdc, nominal Vout unless otherwise noted. Note 2 - Input Reflected Ripple Current (RMS), tested with the circuit as Figure 13 on page 14.



Output Specifications

| Parameter | | Conditions ¹ | Symbol | Min | Тур | Max | Unit |
|---|---------------------------------|--|-----------------------------------|--------|------------|-------|---------------------|
| Factory Voltage Set Point | | V _{IN,DC} = 50 Vdc I _O = 50%I _{O,max} | Vo | 12.10 | 12.25 | 12.35 | Vdc |
| Output Voltage Line Reg | gulation | All | Vo | - | 60 | - | mV |
| Output Voltage Load Re | gulation | All | Vo | - | 200 | - | mV |
| Output Voltage Tempera | ature Regulation | All | Vo | - | - | 0.02 | %/°C |
| Total Regulation | | Over set point, line, load, temperature & life | Vo | 11.50 | - | 12.95 | Vdc |
| Output Voltage Ripple a See Figure 13 for the se | | Measured with a 0.68 uF output cap. to 20 MHz bandwidth; Figure 13 | Vo | - | 50 | - | mV _{PK-PK} |
| Output Current | | All | Ι _Ο | 0 | - | 73.7 | А |
| Output DC Current-limit Inception ² | | All | ۱ ₀ | 80 | - | 127 | А |
| V _o Load Capacitance | | All | Co | 590 | - | 6000 | uF |
| V _o Dynamic Response | Peak Deviation Settling Time | 50% to 75% to 50% I _{O,max} Slew rate = 0.1 A/us | ±V _O T _s | - - | 200 300 | | mV us |
| | Rise Time | I _O = I _{O,max} | T _{rise} | - | - | 50 | mS |
| | Turn-on Delay Time | By DC input | T _{turn-on} | - | - | 200 | mS |
| Turn-on Transient | Turn-on Delay Time | By enable | T _{turn-on} | - | - | 200 | mS |
| | Turn-on Overshoot | All | Vo | - | - | 600 | mV |
| | Turn-off Undershoot | All | Vo | - | - | 600 | mV |
| Remote ON/OFF | Off-state Voltage | All | | 2.4 | - | 15 | Vdc |
| Control (Negative logic) ³ | On-state Voltage | All | | -0.3 | - | 0.8 | Vdc |
| Power Good Function | Power Good State | All | | -0.3 | - | 0.8 | Vdc |
| (Negative logic) ⁴ | Power NOT-good State | All | | 2.4 | - | 5 | Vdc |
| Output Overvoltage Protection ⁵ | | All | | 13.7 | - | 18.5 | Vdc |
| Output Over Temperatu | re Protection ⁶ | Baseplate | Т | 95 | - | 135 | °C |
| Switching Frequency | | All | f _{sw} | - | 165 | - | kHz |
| Logic Pin Voltage ⁷ | | All | | -0.3 | - | 3.6 | Vdc |

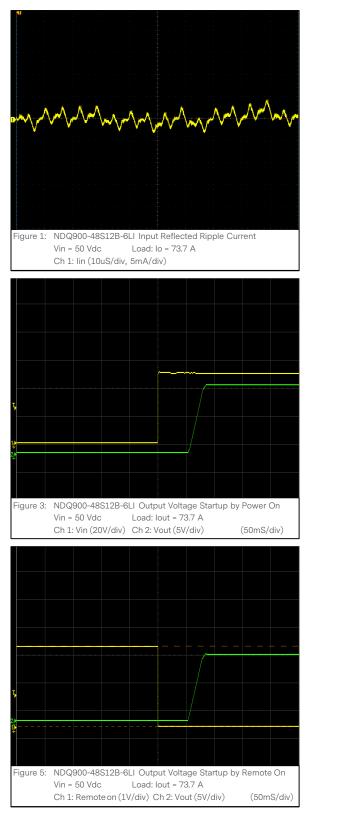
Note 1 - $T_{\rm A}$ = 25 °C, Vin = 50 Vdc, nominal Vout unless otherwise noted. Note 2 - Hiccup: auto-restart when overcurrent condition is removed.

Note 3 - Negative logic default, positive available.

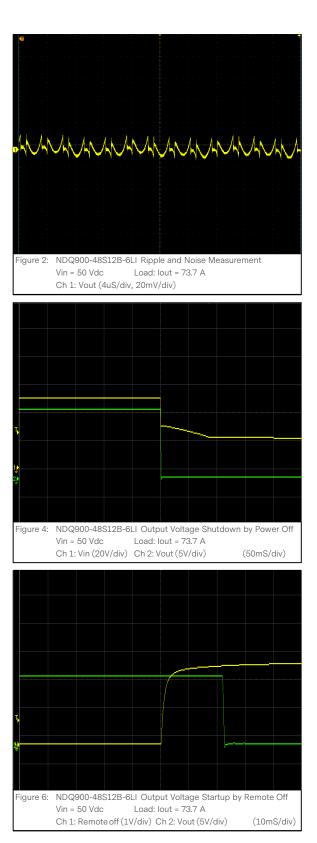
Note 5 - Hiccup: auto-restart when overvoltage condition is removed. Note 6 - Auto recovery. Temperature protect (OTP) test point is the middle of baseplate. Note 7 - Such as Addr, Clock, Data, SMBAlert signal. Voltage reference to Sig_gnd or Vo-.



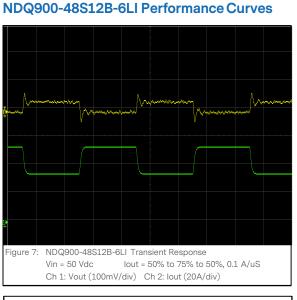
Note 4 - The power good function will exhibit a logic-low when the unit is operating correctly, and a logic-high when the unit is in fault condition and not supplying power. The power good function is open drain, with external pull-up resistor.



NDQ900-48S12B-6LI Performance Curves

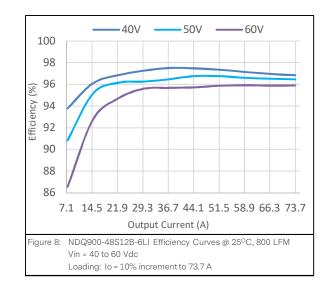






-40V --50V --60V 40 35 Dower Loss (W) 20 25 10 15 15 10 5 7.1 14.5 21.9 29.3 36.7 44.1 51.5 58.9 66.3 73.7 Output Current (A) Figure 9: NDQ900-48S12B-6LI Power Loss @ 25°C, 800 LFM Vin = 40 to 60 Vdc

Loading: Io = 10% increment to 73.7 A

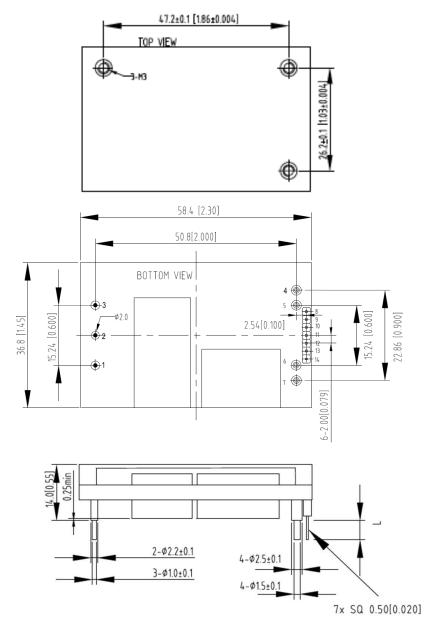






MECHANICAL SPECIFICATIONS

Mechanical Outlines



Note 1 - Dimensions within the box are critical dimensions.

Note 2 - NDQ900-48S12B-6LI has pin 8 to 14,

Note 3 - The minimum clearance from customer PCB is 0.2 mm (0.008 inch).

Note 4 - Depth penetration into base plate, of M3 screws used at baseplate mounting holes, not to exceed maximum of 3.0 mm.



MECHANICAL SPECIFICATIONS

Pin Length option

| Device code suffix | L |
|--------------------|----------------|
| -4 | 4.6 mm±0.25 mm |
| -6 | 3.8 mm±0.25 mm |
| -8 | 2.8 mm±0.25 mm |
| None | 5.8 mm±0.25 mm |

Pin Designations

| Pin No | Name | Function | Optional |
|--------|---------------|-------------------------|----------|
| 1 | Vin+ | Positive input voltage | |
| 2 | Remote ON/OFF | Remote control | |
| 3 | Vin- | Negative input voltage | |
| 4 | Vo- | NA | Yes |
| 5 | Vo- | Negative output voltage | |
| 6 | Vo+ | Positive output voltage | |
| 7 | Vo+ | NA | Yes |
| 8 | PG | Power Good | Yes |
| 9 | Sig_gnd | PMBus Interface | Yes |
| 10 | Data | PMBus Interface | Yes |
| 11 | SMBAlert | PMBus Interface | Yes |
| 12 | Clock | PMBus Interface | Yes |
| 13 | Addr | PMBus Interface | Yes |
| 14 | Ishare | Current Share | Yes |



ENVIRONMENTAL SPECIFICATIONS

Input Fusing

The internal fuse is fast blow type. An external fuse is recommended. To meet international safety requirements, recommended rating is 50 A /150 Vdc for the converter.

EMC Immunity

NDQ900-48S12B series power supply is designed to meet the following EMC immunity specifications:

| Table 4. Environmental Specifications | | | | |
|--|--|----------|--|--|
| Document | Description | Criteria | | |
| EN55032, DC input port, Class A | Conducted EMI Limits, DC input port | / | | |
| IEC/EN 61000-4-2, Enclosure Port, Level 3 | Electromagnetic Compatibility (EMC) - Testing and measurement techniques: Electrostatic discharge immunity test | В | | |
| IEC/EN 61000-4-4, Level 3 | Electromagnetic Compatibility (EMC) - Testing and measurement techniques: Electrical Fast Transient. DC input port | В | | |
| IEC/EN 61000-4-6, Level 2 | Electromagnetic Compatibility (EMC) - Testing and measurement techniques: Continuous Conducted Interference. DC input port | А | | |
| EN61000-4-29, DC input port | Immunity to Voltage Dips and Short Interruptions and Voltage Variations | В | | |

Criterion A: Normal performance during and after test.

Criterion B: Output voltage fluctuation or reset is allowed during the test, but recovers to its normal performance automatically after the disturbance ceases. Criterion C: Temporary loss of output, the correction of which requires operator intervention.

Criterion D: Loss of output which is not recoverable, owing to damage to hardware.

Safety Certifications

The NDQ900-48S12B series power supply is intended for inclusion in other equipment and the installer must ensure that it is in compliance with all the requirements of the end application. This product is only for inclusion by professional installers within other equipment and must not be operated as a stand alone product.

| Table 5. Safety Certifications for NDQ900-48S12B Series Power Supply System | | | | |
|---|---------|--|--|--|
| Standard | Agency | Description | | |
| UL/CSA62368-1 | UL+CUL | US and Canada Requirements | | |
| EN62368-1 | TUV-SUD | European Requirements | | |
| IEC62368-1 | IEC | International Requirements | | |
| CE | CE | CE Marking | | |
| UL94 | UL | Materials meet V-0 flammability rating | | |
| UKCA | | UK Requirements | | |



ENVIRONMENTAL SPECIFICATIONS

Operating Temperature

The NDQ900-48S12B series power supply will start and operate within stated specifications at an ambient temperature from -40°C to 85°C under all load conditions. The storage temperature is -55°C to 125°C.

Thermal Considerations - Baseplate module

NDQ900-48S12B is designed to operate in different thermal environments and sufficient cooling must be provided. Proper cooling can be verified by measuring the temperature at the test points as shown in the Figure 10. The temperature at these test points should not exceed the maximum values in Table 6.

For a typical application, Figure 11 shows the derating of output current vs. ambient air temperature at different air velocity@54V input with a 0.6" heat sink.

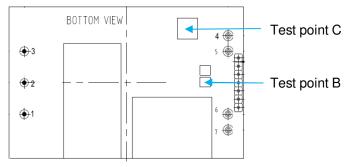


Figure 10 Temperature test points

| Table 6. Temperature Limit of the Test Points | | | | | |
|---|-------------------------------------|--|--|--|--|
| Test Point | Temperature Limit (^O C) | | | | |
| Test point A (Baseplate middle) | 106 | | | | |
| Test point B | 120 | | | | |
| Test point C | 110 | | | | |



NDQ900-48S12B

ENVIRONMENTAL SPECIFICATIONS

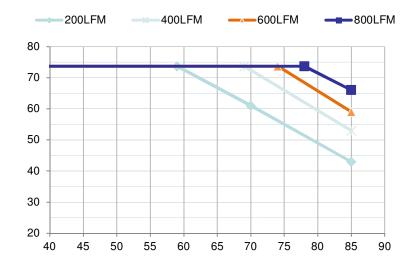


Figure 11 NDQ900-48S12B-6LI with 0.6" heat sink, output power derating at 54Vin, air flowing across the converter from Vin- to Vin+

Qualification Testing

| Table 7. Qualification Testing | 9 | |
|--------------------------------|------------|--|
| Parameter | Unit (pcs) | Test condition |
| HALT test | 2 | Operating limit: Ta,min -20°C to Ta,max +25°C, 10°C step, $V_{IN,DC}$ = min to max, 0 to 100% load Vibration limit: > 25 G |
| Vibration | 2 | Frequency range: 5 Hz to 20 Hz, 20 Hz to 200 Hz, A.S.D: 1.0 m2/s3, -3 db/oct Axes of vibration: X/Y/Z. Time: 30 min/axis. Non-operational. |
| Mechanical Shock | 2 | Type: half sine, Acceleration: 30 g, Duration: 6 ms, Directions: 6 Number of shock: 3 times/face. Non-operational. |
| Thermal Shock | 3 | -55°C to 125°C, Temp dwell time: 30 min, Temp change rate: 20°C/min, Unit temperature 20 cycles |
| Thermal Cycling | 3 | -40°C to 85°C, temperature change rate: 1°C/min, cycles: 2 cycles |
| Humidity | 3 | 40°C, 95%RH, 48 h |
| MTBF | • | Telcordia, SR332 Method 1 Case 1, 1.5 MHrs typically |



Typical Application

Below is the typical application of the NDQ900-48S12B series power supply.

Power Module

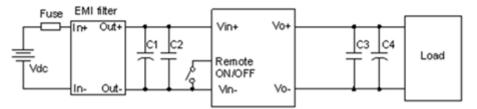


Figure 12 Typical application

C1: 300 μ F/100V electrolytic capacitor (2*47 μ F/80V OSCON cap+2*100 μ F/100V Nichicon cap)

C2: $0.1 \mu \text{F}/100 \text{V}$ X7R ceramic capacitor

C3: 1PCS 1 $\mu\text{F}/16\text{V}/\text{X7S}$ capacitor

C4: 4000 $\mu\text{F}/16\text{V}$ electrolytic capacitor, OSCON or POSCAP

Fuse: External fast blow fuse with a rating of 50A/150Vdc. The recommended fuse model is WM55-50 from Walter Electronic.



Input Ripple & Inrush Current and Output Ripple & Noise Test Configuration

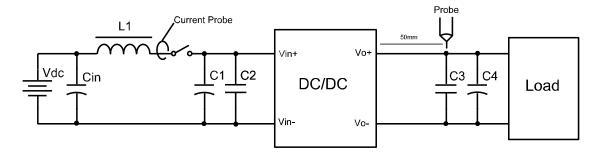


Figure 13 Input ripple & inrush current & output ripple and noise test configuration

Vdc: DC power supply

L1: 12µH

Cin: 300µF/100V typical

C1 to C4: See Figure 12

Note: Using a coaxial cable with a 50 hm termination resistor and 0.68μ F ceramic capacitor in series to test output ripple & noise is recommended.

Power Good Function

The NDQ900-48S12B series has a power good function, the Power Good pin is open drain need external pull-up to high level.

When the unit is operating correctly, supplying power and all parameters are within specification, a logic-Low voltage will be present on this pin.

When the unit is NOT operating correctly - either is under a mode of protection (over temperature, overcurrent or overvoltage) that is causing the unit to "shut-down" and not supply power, or, if the unit has failed, there will be logic-High voltage present on this pin. The high level will not exceed 5V.



EMC test conditions

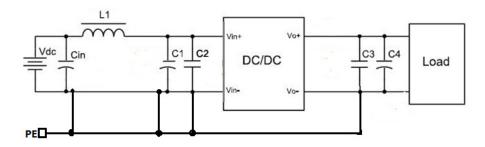


Figure 14 EMC test conditions

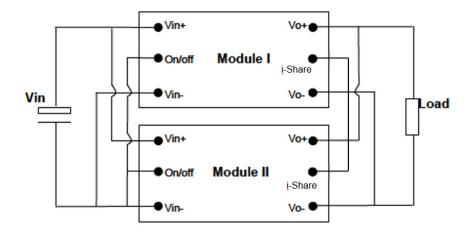
- Cin: 2*10uF/100V/X7R + 4*4.7uF/100V/X7R ceramic capacitor
- C1: 241µF/100V electrolytic capacitor (2*47uF/80V OSCON cap+147uF/100V Nichicon cap)
- C2: 2*2.2uF/100V/X7R + 1uF/100V/X7R ceramic capacitor
- C3: 10*22uF/16V/X7R ceramic capacitor
- C4: 4000μ F/16V electrolytic capacitor, OSCON
- L1: 5.1uH inductor

Fuse: External fast blow fuse with a rating of 50A /150Vdc. The recommended fuse model is WM55-50 from Walter Electronic.



Current Share Function

The modules are capable of operating in parallel and realizing current sharing by active current sharing method. There is a current sharing pin. By connecting the Vin pin the Vo pin and the Ishare pin of the parallel module together, the current sharing can be realized automatically. Max parallel module number is 2 (parallel maximum load \leq 118 A).



If system has no redundancy requirement, the module can be parallel directly for higher power without adding external ORing-FET; whereas, if the redundancy function is required, the external ORing-FET should be added.

For a normal parallel operation, the following precautions must be observed:

• The current sharing accuracy equation is:

X% = | Io - (Itotal / N) | / Irated, Where:

lo is the output current of per module;

Itotal is the total load current;

N is parallel module numbers;

Irated is the rated full load current of per module.

- To ensure a better steady current sharing accuracy, below design guideline should be followed:
- a) The inputs of the converters must be connected to the same voltage source, and the PCB trace resistance from input voltage source to Vin+ and Vin- of each converter should be equalized as much as possible.
- b) The PCB trace resistance from each converter's output to the load should be equalized as much as possible.
- c) For accurate current sharing accuracy test, the module should be soldered in order to avoid the unbalance of the touch resistance between the modules to the test board.
- To ensure the parallel module can start up monotonically without trigging the OCP circuit, below design guideline should be followed:
- a) Before all the parallel module finished start up, the total load current should be lower than the 50% rated current of one module.
- b) The ON/OFF pin of the converters should be connected together to keep the parallel modules start up at the same time.
- c) The undervoltage lockout point will slightly vary from unit to unit. The dv/dt of the rising edge of the input source voltage must be greater than 1 V/ms to ensure that the parallel module start up at the same time.



SOLDERING INFORMATION

Soldering

Generally, as the most common mass soldering method for the solder attachment, wave soldering is used for through-hole power modules and reflow soldering is used for surface-mount ones.

Reflow soldering is not a suggested method for through-hole power modules due to process challenges that can result in reduced module reliability. If you have this kind of application requirement, please contact sales or FAE for further information and recommendations.

Wave Soldering

When wave soldering is used, the temperature on pins is specified to maximum 255°C for maximum 7 s.

When soldering by hand, the iron temperature should be maintained at 300°C to 380°C and applied to the converter pins for less than 10 s. Longer exposure can cause internal damage to the converter.

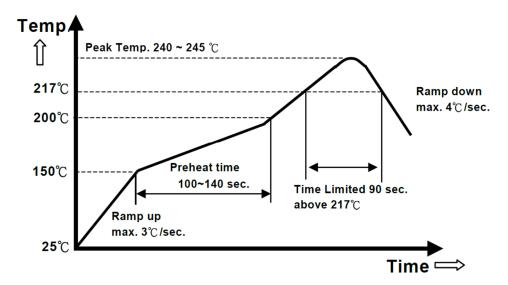
Cleaning of solder joint can be performed with cleaning solvent IPA or simulative.

Reflow Soldering

High temperature and long soldering time will result in IMC layer increasing in thickness and thereby shorten the solder joint lifetime. Therefore the peak temperature over 245°C is not suggested due to the potential reliability risk of components under continuous high-temperature. In the meanwhile, the soldering time of temperature above 217°C should be less than 90 s.

Please refer to following fig for recommended temperature profile parameters.

Shielding cap is requested to mount on DCDC module if with heat-spreader/heat-sink, to prevent the customer side high temperature of reflow to re-melt the DCDC module's internal component's soldering joint.



Note: The temperature is measured on the pins of power module at the solder joint.



PMBus[™] General Instructions

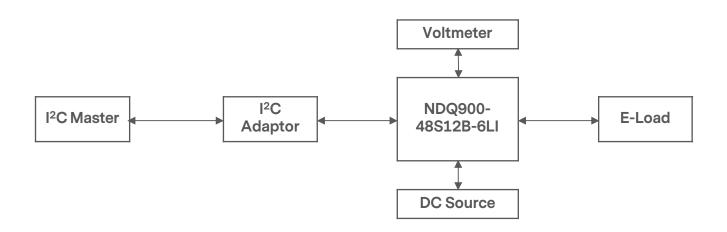
The NDQ900-48S12B-6LI is compliant with the industry standard PMBus[™] protocol for monitoring and control of the power supply via the I²C interface port. Detailed timing and electrical characteristics of the PMBus[™] can be found in the PMB Power Management Protocol Specification, Part 1, revision 1.2, available at http://PMBus.org.

The module supports 100 kHz bus timing requirements. The module shall stretch the clock, as long as it does not exceed the maximum clock LO period of 35 ms. It is recommended to always use PEC (Packet Error Check) when communicating via PMBus.

The module supports a subset of the commands in the PMBus[™] 1.2 specification. Most all of the controller parameters can be programmed using the PMBus[™] and stored as defaults for later use. All commands that require data input or output use the linear format. The exponent of the data words is fixed at a reasonable value for the command and altering the exponent is not supported. Direct format data input or output is not supported by the module. The supported commands are described in greater detail below. The module contains non-volatile memory that is used to store configuration settings and scale factors. The settings programmed into the device are not automatically saved into this non-volatile memory though. The STORE_DEFAULT_ALL command must be used to commit the current settings to non-volatile memory as device defaults. The settings that are capable of being stored in non-volatile memory are noted in their detailed descriptions.

Equipment Setup

The following is typical I²C communication setup:



PMBus[™] Signal Interface Characteristics

| Table 8. PMBus [™] Signal Interface Characteristics ¹ | | | | | |
|---|----------------------|------|-----|-----|------|
| Parameter | Conditions | Min | Тур | Max | Unit |
| Input High Voltage (Clock, Data, Ishare) | | 2.1 | - | 3.6 | V |
| Input Low Voltage (Clock, Data, PG, Ishare) | | 0 | - | 0.8 | V |
| Input High Level Current (Clock, Data, PG) | | -2.5 | - | 2.5 | mA |
| Output Low Voltage (SMBAlert, Clock, Data) | I _O = 2mA | - | - | 0.4 | V |
| PMBus Operation Frequency ² | | | 100 | | kHz |

Note 1 - The max current of Sig_gnd pin is 0.4A.

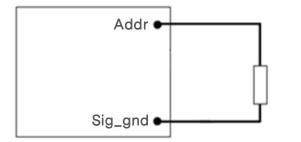
Note 2 - For applications where PMBus frequency at 400 kHz is required, please contact Advanced Energy technical support.



PMBus™ SPECIFICATIONS

PMBus[™] Addressing

The module has flexible PMBus[™] addressing capability. By connecting different resistors from Addr pin to Sig_gnd pin, 15 possible addresses can be acquired. The 7-bit PMBus[™] address is defined by the value of the resistor as shown in the table below, and +/-1% resistor accuracy is acceptable. If there is any resistance exceeding the requested range, address 126 will be returned.



| Resistor (kOhm) | 7-bit Address | 8-bit Address |
|-----------------|---------------|---------------|
| 0 | 96 | 0xC0h |
| 10 | 96 | 0xC0h |
| 15 | 97 | 0xC2h |
| 21 | 98 | 0xC4h |
| 28 | 99 | 0xC6h |
| 35.7 | 100 | 0xC8h |
| 45.3 | 101 | 0xCAh |
| 56.2 | 102 | 0xCCh |
| 69.8 | 103 | 0xCEh |
| 88.7 | 104 | 0xD0h |
| 107 | 105 | 0xD2h |
| 130 | 106 | 0xD4h |
| 158 | 107 | 0xD6h |
| 191 | 108 | 0xD8h |
| 232 | 109 | 0xDAh |
| Open | 127 | 0xFEh |



PMBus[™] Adjustable Input Undervoltage Lockout

The module allows adjustment of the input undervoltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For both the VIN_ON and VIN_OFF commands, possible values range from 34.000 to 40.000 V in 0.125 V steps. VIN_ON must be 1.5 V greater than VIN_OFF.

Both the VIN_ON and VIN_OFF commands use the "linear" format with two data bytes. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -3 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid. The data associated with VIN_ON and VIN_OFF can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

PMBus[™] Adjustable Soft Start Delay and Rise Time

The soft start delay and rise time can be adjusted in the module via PMBusTM. The TON_DELAY command sets the delay time in ms, and allows choosing delay times between 10 ms and 200 ms, with resolution of 0.5 ms. The TON_RISE command sets the rise time in ms, and allows choosing soft start times between 20 ms and 50 ms, with resolution of 0.5 ms. When setting TON_RISE, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. Both the TON_RISE and TON_DELAY commands use the "linear" format with two data bytes. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -1 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid. The data associated with TON_RISE and TON_DELAY can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Output Voltage Adjustment Using the PMBus[™]

The module output voltage set point is adjusted using the VOUT_COMMAND. The output voltage setting uses the linear data format, with the 16 bits of the VOUT_COMMAND formatted as an unsigned mantissa, and a fixed exponent of -12 (decimal) (read from VOUT_MODE).

The resolution is 0.244 mV . The data associated with VOUT_COMMAND can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Range limits (max/min): 13.2/10.8 V

Notes:

- Trim up @ Vin = 44 to 60 V,
- When trimmed up, the output power not to exceed 900 W;
- When operated in parallel operation, it is not recommend to use trim function.

(If trim function is intended for use when two units are in sharing connection, please contact Advanced Energy Technical support for guidance).

Measuring Input Voltage Using the PMBus[™]

The module can provide input voltage information using the READ_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -3 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.



Measuring Input Current Using the PMBus[™]

The module can provide input current information using the READ_IIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -2 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.

Measuring Output Voltage Using the PMBus[™]

The module can provide output voltage information using the READ_VOUT command. The command returns two bytes of data in the linear format, with the 16 bits of the READ_VOUT formatted as an unsigned mantissa, and a fixed exponent of -12 (decimal).

Measuring Output Current Using the PMBus[™]

The module measures output current by using the output filter inductor winding resistance as a current sense element. The module can provide output current information using the READ_IOUT command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -2 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid. The READ_IOUT command provides module average output current information. This command only supports positive current sourced from the module. If the converter is sinking current a reading of 0 is provided.

Measuring the Temperature Using the PMBus[™]

The module can provide temperature information using the READ_TEMPERATURE_1 command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data byte form the two's complement representation of the exponent, which is fixed at -2 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa.

Note that the module's temperature sensor is located close to the module hot spot OTP test point and is subjected to temperatures higher than the ambient air temperature near the module. The temperature and temperature reading will be highly influenced by module load and airflow conditions.

Black Box

There is a black box function realized by 22 pages of D-flash (20 K erase cycles up to 120^oC hotspot temp). The first page is used to save the page number where the newest history event is recorded. A further 21 pages with 19 byte per page, are assigned to record 21 history events. The fault time is also recorded. The fault time is the time from the last Vo turn on until the time of the fault occurs. The following fault events can trigger recording of history event data to the black box: Vin UVP, Vin OVP, Vout OVP, Vout OCP, and OTP.

Note: An input UVP event may not be recorded during high slew rate loss of input.

PMBus[™] Enabled On/Off

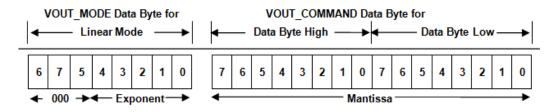
The module can also be turned on and off via the PMBus[™] interface. The OPERATION command is used to actually turn the module on and off via the PMBus[™], Bit [7] in the OPERATION command data byte enables the module, with the following functions:

- 0 : Output is disabled
- 1 : Output is enabled



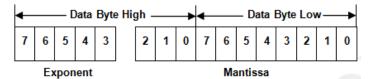
PMBus[™] Data Format

For commands that set or report any voltage thresholds related to output voltage (including VOUT_COMMAND, VOUT_MARGIN, POWER_GOOD and READ_VOUT), the module supports the linear data format consisting of a two byte value with a 16-bit, unsigned mantissa, and a fixed exponent of -12. The format of the two data bytes is shown below:



The value of the number is then given by Value = Mantissa x 2^{-12}

For commands that set all other thresholds, voltages or report such quantities, the module supports the linear data format consisting of a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa x 2^{Exponent}

Measurement System Characteristics

| Table 9. Measurement System Characteristics | | | | | |
|--|---|------|-------|-----|------|
| Parameter | Conditions | Min | Тур | Max | Unit |
| | $I_{\rm O}$ = 60% to 100% $I_{\rm O,max}$ | -8 | - | 8 | % |
| Output current reading accuracy ¹ | I _O = 0% to 60% I _{O,max} | -4.5 | - | 4.5 | А |
| Output current reading resolution ¹ | | - | 0.25 | - | А |
| Vo reading accuracy ¹ | | -2 | 1 | 2 | % |
| Vo reading resolution ¹ | | - | 0.25 | - | V |
| Vin reading accuracy ¹ | | -4 | - | 4 | % |
| Vin reading resolution ¹ | | - | 0.125 | - | V |
| Temperature reading accuracy | T _A > 0°C | - | 3 | - | °C |
| Temperature reading resolution | T _A > 0°C | - | 1 | - | °C |

Note 1 – Current reading accuracy and resolution at typical Vonom when the temperature above zero.



Reading the Status of the Module using the PMBus[™]

The module supports a number of status information commands implemented in PMBus[™]. However, not all features are supported in these commands. A "X" in the FLAG cell indicates the bit is not supported.

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

| Tigit byte | | | | |
|--------------|-----------------------------|---------------|--|--|
| Bit Position | Flag | Default Value | | |
| 15 | VOUT fault | 0 | | |
| 14 | IOUT fault or warning | 0 | | |
| 13 | Input Voltage fault | 0 | | |
| 12 | Х | 0 | | |
| 11 | Power Good (Negative logic) | 0 | | |
| 10 | Х | 0 | | |
| 9 | Х | 0 | | |
| 8 | Х | 0 | | |

High Byte

Low Byte

| Bit Position | Flag | Default Value |
|--------------|------------------|---------------|
| 7 | Х | 0 |
| 6 | OFF | 0 |
| 5 | VOUT Overvoltage | 0 |
| 4 | IOUT Overcurrent | 0 |
| 3 | VIN Undervoltage | 0 |
| 2 | Temperature | 0 |
| 1 | CML (Command) | 0 |
| 0 | Х | 0 |



| Bit Position | Flag | Default Value |
|--------------|----------------------------|---------------|
| 7 | VOUT OV Fault | 0 |
| 6 | Output overvoltage warning | 0 |
| 5 | Х | 0 |
| 4 | Х | 0 |
| 3 | Х | 0 |
| 2 | Х | 0 |
| 1 | Х | 0 |
| 0 | Х | 0 |

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

STATUS_IOUT: Returns one byte of information relating to the status of the module's output current related faults.

| Bit Position | Flag | Default Value |
|--------------|-----------------|---------------|
| 7 | IOUT OC Fault | 0 |
| 6 | Х | 0 |
| 5 | IOUT OC Warning | 0 |
| 4 | Х | 0 |
| 3 | Х | 0 |
| 2 | Х | 0 |
| 1 | Х | 0 |
| 0 | Х | 0 |

STATUS_INPUT: Returns one byte of information relating to the status of the module's input voltage related faults.

| Bit Position | Flag | Default Value |
|--------------|----------------------------|---------------|
| 7 | VIN OV Fault | 0 |
| 6 | Input overvoltage warning | 0 |
| 5 | Input undervoltage warning | 0 |
| 4 | VIN UV Fault | 0 |
| 3 | Х | 0 |
| 2 | Х | 0 |
| 1 | Х | 0 |
| 0 | Х | 0 |



| Bit Position | Flag | Default Value |
|--------------|------------|---------------|
| 7 | OT Fault | 0 |
| 6 | OT Warning | 0 |
| 5 | Х | 0 |
| 4 | Х | 0 |
| 3 | Х | 0 |
| 2 | Х | 0 |
| 1 | Х | 0 |
| 0 | Х | 0 |

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

All of the warning or fault bits set in the status registers remain set, even if the fault or warning condition is removed or corrected, until one of the following occur:

- The device receives a CLEAR_FAULTS command
- Bias power is removed from the module



Summary of Supported PMBus[™] Commands

This section outlines the PMBus[™] command support for this bus converter. Each supported command is outlined in order of increasing command codes with a quick reference table of all supported commands included at the end of the section. Each command will have the following basic information.

- Command Name [Code]
- Command support
- Additional information may be provided in tabular form or other format, if necessary.

OPERATION [0x01]

Command support: On/Off Immediate

| Bit Position | Purpose | Bit Value | Meaning |
|-----------------------------|--------------------|-----------|--------------------|
| 7 Enable/Disable the module | Enable/Disable the | 1 | Output is enabled |
| | module | 0 | Output is disabled |
| 6 | Reserved | | |
| 5:4 | Vout Command | 00 | No margin |
| 3:0 | Reserved | | |

CLEAR_FAULTS [0x03]

Command support: All functionality

WRITE PROTECTION [0x10]

Command support: Supported. Factory default: 0x10 - Indicates protection is enabled.

| Bit Position | Purpose | Bit Value | Meaning |
|------------------------------|--------------------|-----------|------------------------|
| 7 Enable/Disab protection | Enable/Disable the | 1 | Protection is enabled |
| | protection | 0 | Protection is disabled |
| 6:0 | Reserved | | |

STORE_DEFAULT_ALL [0x11]

Command support: All functionality - Stores operating parameters to E²prom memory.

RESTORE_DEFAULT_ALL [0x12]

Command support: All functionality - Restores operating parameters from E²prom memory.



VOUT_MODE [0x20]

Command support: Supported. Factory default: 0x14 - Indicates linear mode with exp = -12.

| Format | 8 bit unsigned (bit field) | | | | | | | |
|---------------|----------------------------|---|---|-------------------------|---|---|---|---|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Access | R | R | R | R | R | R | R | R |
| Function | Mode (linear) | | | 2's complement exponent | | | | |
| Default Value | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |

VOUT_COMMAND [0x21]

Data format: 16 bit unsigned mantissa (implied exponent per VOUT_MODE)

Factory default: 12.25 V

Range limits (max/min): 13.2/10.8 V

Unit: volt

Notes:

- Trim up within the input voltage range: Vin = 44 to 60 V.
- When trimming up, make sure the output power does not exceed 900 W.
- When operating in parallel operation, it is not to recommend to use trim function.

(If trim function is intended for use when two units are in current sharing connection, please contact Advanced Energy Technical support for guidance).

VIN_ON [0x35]

Range limits (max/min): 40/35

Unit: volt

Command support: All functionality

Note: Special interlock checks between VIN_ON and VIN_OFF maintain a hysteresis gap of 1.5 V minimum and do not allow the OFF level to be higher than and ON level.

VIN_OFF [0x36]

Range limits (max/min): 39/34

Unit: volt

Command support: All functionality

Note: Special interlock checks between VIN_ON and VIN_OFF maintain a hysteresis gap of 1.5 V minimum and do not allow the OFF level to be higher than and ON level.

VOUT_OV_WARNING_LIMIT [0x42]

Range limits (max/min): 15/13.5 Unit: volt Command support: All functionality Note: Value must be the same or less than VOUT_OV_FAULT_LIMIT value.



VOUT_OV_FAULT_LIMIT [0x40]

Range limits (max/min): 15/13.5 Unit: volt Command support: All functionality Note: Range cross-check-value must be greater than VOUT_COMMAND value.

IOUT_OC_FAULT_LIMIT [0x46]

Range limits (max/min): 110/80 Unit: amp Command support: All functionality Note: Range cross-check-value must be greater than IOUT_OC_WARN_LIMIT value.

IOUT_OC_WARN_LIMIT [0x4A]

Range limits (max/min): 110/78 Unit: amp Command support: Read/write support, functionality complete Note: Range cross-check-value must be the same or less than IOUT_OC_FAULT_LIMIT value.

OT_FAULT_LIMIT [0x4F]

Range limits (max/min): 127/25 Unit: degC Command support: All functionality Note: Range cross-check-value must be greater than OT_WARN_LIMIT value.

OT_WARN_LIMIT [0x51]

Range limits (max/min): 120/25 Unit: degC Command support: All functionality Note: Range cross-check-value must be less than OT_FAULT_LIMIT value.

VIN_OV_FAULT_LIMIT [0x55]

Range limits (max/min): 66/61 Unit: volt Command support: All functionality



STATUS_WORD [0x79]

Command support: full implementation for supported functions, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|---------|----------------------------|---------|----------|----------|----------|----------|----------|--|--|--|
| Bit Position | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | VOUT | IOUT | INPUT | Reserved | Reserved | Reserved | Reserved | Reserved | | | |

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|----------|----------------------------|-----------------------|-------------------|------------------|---------|---------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | Reserved | OUTPUT_ OFF | VOUT_ OV_ FAULT | IOUT_OC _FAULT | VIN_UV_ FAULT | TEMP | CML | Reserved | | | |

STATUS_VOUT [0x7A]

Command support: VOUT_OV_FAULT and VOUT_OV_WARN supported, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|-------------------|----------------------------|----------|----------|----------|----------|----------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | VOUT_OV _FAULT | VOUT_OV _WARN | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | | | |

STATUS_IOUT [0x7B]

Command support: IOUT_OC_FAULT and IOUT_OC_WARN supported, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|-------------------|----------------------------|------------------|----------|----------|----------|----------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | IOUT_OC _FAULT | Reserved | IOUT_OC _WARN | Reserved | Reserved | Reserved | Reserved | Reserved | | | |

STATUS_INPUT [0x7C]

Command support: VIN_OV_FAULT, VIN_OV_WARN, VIN_UV_WARN and VIN_UV_FAULT supported, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|------------------|----------------------------|-----------------|------------------|----------|----------|----------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | VIN_OV_ FAULT | VIN_OV_ WARN | VIN_UV_ WARN | VIN_UV_ FAULT | Reserved | Reserved | Reserved | Reserved | | | |



STATUS_TEMPERATURE [0x7D]

Command support: OT_WARN, OT_FAULT supported, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|----------|----------------------------|---------|---------|----------|----------|----------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | OT_FAULT | OT_WARN | Reserve | Reserve | Reserved | Reserved | Reserved | Reserved | | | |

STATUS_CML [0x7E]

Command support: Invalid/Unsupported Command Received, Invalid/Unsupported Data Received and Packet Error Check Failed supported, all bit reset supported

| Format | | 8 bit unsigned (bit field) | | | | | | | | | |
|--------------|--|---|------------------------------------|---------|----------|----------|----------|----------|--|--|--|
| Bit Position | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| Access | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | R/Reset | | | |
| Function | Invalid/Un supported Command Received | Invalid/Un supported Data Received | Packet Error Check Failed | Reserve | Reserved | Reserved | Reserved | Reserved | | | |

READ_VIN [0x88]

Command support: full support

READ_VOUT [0x8B]

Command support: full support

READ_IOUT [0x8C]

Command support: full support

READ_TEMPERATURE_1 [0x8D]

Command support: full support

PMBus_REVISION [0x98]

Command support: full read support

PMBus_CMD_MFR_ID [0x99]

Command support: full read support

PMBus_CMD_MFR_MODEL [0x9A]

Command support: full read support

MFR_FW_REV [0x9B]

Command support: full read support

PMBus_CMD_MFR_LOCATION [0x9C]

Command support: full read/write support

PMBus_CMD_MFR_SERIAL [0x9E]

Command support: full read/write support



CLEAR BLACKBOX [0XB6]

Command support: write support

Write 0xAA to the command, blackbox can be cleared and all history event data is set to 0.

BLACKBOX_EN [0xDF]

The black box can be set to stop recording once full (21 fault events recorded) or to overwrite the oldest fault event data with the next fault event data once full. The module is shipped with a default setting of overwrite enabled.

| Bit Position | Purpose | Bit Value | Meaning |
|--------------|------------------------------|-----------|--------------------------------|
| 7:1 | Reserved | | |
| 0 | Enable/Disable the black box | 1 | Overwrite function is enabled |
| 0 | overwrite function | 0 | Overwrite function is disabled |

If overwrite function is disabled, black box only record 21 faults, then it will lock and no more faults will be recorded. If overwrite function is enabled, when fault log is full, the new fault will start overwriting previous faults, starting from entry 0.



History Event Read Section

0xE1 command: Write the Offset Value to Slave to decide which history data for read.

0xE0 command: Read the history data after 0xE1 command.

READ HISTORY EVENT OFFSET (0XE1):

Send command 0XE1 and read one byte, it will return the next event log offset value x.

| Start | Device Address & R/W | | Repeated Start | Device Address & R/W |
|------------------------|----------------------|-----|----------------|----------------------|
| Event log offset value | | PEC | Stop | |

SET HISTORY EVENT OFFSET [0XE1]

Reading 0xE1 yields the value x of the next history event (to be recorded in the future). To read the last history event (the most recent history event recorded), send write command 0XE1 with offset value of x-1. Then send read command 0XE0 and the last event data will be read back. There are 21 possible values for the offset (0-20), if the number of history events is larger than 20, 0XE1 will be reset from 20 to 0.

| Start Devi | evice Address & R/W | Command byte(0XE1) | Offset value | PEC | Stop |
|------------|---------------------|--------------------|--------------|-----|------|
|------------|---------------------|--------------------|--------------|-----|------|

READ_HISTORY EVENTS [0xE0]

| Start | Device Address & R/W | | | Command byte(0XE0) | | | Repeated Start | | |
|------------------------|----------------------|--------------------|--------|---------------------------|------------------|----------------------|--------------------|------------|------|
| Device Address & R/W | EVENT# | Status_Word | _High_ | Byte | Status_Word_Low_ | | Status_Vo | out | |
| Status_lout | Status_Input | Status_Temperature | | 9 | Status_cml | | Vin_data_high_byte | | oyte |
| Vin_data_low_byte | Vout_data_high_byte | 9 | Vout_ | _data_low_byte | | lout_data_high_byte | | | |
| lout_data_low_byte | temperature_data_h | high_byte te | | temperature_data_low_byte | | Fault time_first_byt | | first_byte | |
| Fault time_second_byte | Fault time_third_by | d_byte | | Fault time_fourth_byte | | PEC |) | | Stop |

Fault time: Record the operating time since last fault, up to 256 days. Fault time_first_byte is seconds; Fault time_second_byte is minutes; Fault time_third_byte is hours; Fault time_fourth_byte is days. If no fault occurs after 256 days of operating time the counter will reset and begin a new count.



NDQ900-48S12B-6LI Supported PMBus[™] Command list

| Command Code | Command Name | Default Value | Access Type | Data Bytes | Data Format | Description |
|-----------------|---------------------|------------------|----------------|---------------|--------------------------|--|
| 01h | OPERATION | 80h | R/W | 1 | Bit field | Used to turn the unit ON/OFF |
| 02h | ON_OFF_CONFIG | 1Dh | R/W | 1 | Bit field | 0x1Dh(Neg Logic); 0x1Fh(Pos Logic) |
| 03h | CLEAR_FAULTS | - | Send | 1 | N/A | Clear any fault bits that have been set |
| 10h | WRITE_PROTECTION | 10h | R/W | 1 | Bit field | Set or Clear the bit of Write protection |
| 11h | STORE_DEFAULT_ALL | - | Send | 0 | N/A | Stores operating parameters to E ² prom memory |
| 12h | RESTORE_DEFAULT_ALL | - | Send | 0 | N/A | Restores operating parameters from E ² prom memory |
| 19h | CAPABILITY | B0h | R | 1 | Bit field | Information of a PMBus device |
| 20h | VOUT_MODE | 14h | R | 1 | Mode+exp | To read VOUT data format |
| 21h | VOUT_COMMAND | - | R/W | 2 | VOUT linear | Set the output voltage |
| 33h | FREQUENCY_SWITCH | - | R | 2 | Linear, Exponent is 0 | Read the switching frequency |
| 35h | VIN_ON | - | R/W | 2 | Linear | Set the turn on voltage threshold of vin |
| 36h | VIN_OFF | - | R/W | 2 | Linear | Set the turn off voltage threshold of vin |
| 40h | VOUT_OV_FAULT_LIMIT | - | R/W | 2 | VOUT linear | Set the output overvoltage fault threshold |
| 42h | VOUT_OV_WARN_LIMIT | - | R/W | 2 | VOUT linear | Set the output overvoltage warn threshold |
| 46h | IOUT_OC_FAULT_LIMIT | - | R/W | 2 | Linear | Set the output overcurrent fault threshold |
| 4Ah | IOUT_OC_WARN_LIMIT | - | R/W | 2 | Linear | Set the output overcurrent warn threshold |
| 4Fh | OT_FAULT_LIMIT | - | R/W | 2 | Linear | Set the over temperature fault threshold |
| 51h | OT_WARN_LIMIT | - | R/W | 2 | Linear | Set the over temperature warn threshold |
| 55h | VIN_OV_FAULT_LIMIT | - | R/W | 2 | Linear | Set the input overvoltage fault threshold |
| 5Eh | POWER_GOOD_ON | 9000h | R/W | 2 | VOUT linear | Set POWER GOOD on flip level |
| 5Fh | POWER_GOOD_OFF | 8000h | R/W | 2 | VOUT linear | Set POWER GOOD off flip level |
| 60h | TON_DELAY | - | R/W | 2 | Linear | Set the power on delay time |
| 61h | TON_RISE | - | R/W | 2 | Linear | Set the power on rise time |
| 79h | STATUS_WORD | - | R | 2 | Bit field | Returns the information with a summary of the module's fault/warning |
| 7Ah | STATUS_VOUT | - | R | 1 | Bit field | Returns the information of the module's output voltage related fault/warning |
| 7Bh | STATUS_IOUT | - | R | 1 | Bit field | Returns the information of the module's output current related fault/warning |
| 7Ch | STATUS_INPUT | - | R | 1 | Bit field | Returns the information of the module's input overvoltage and undervoltage fault |
| 7Dh | STATUS_TEMPERATURE | - | R | 1 | Bit field | Returns the information of the module's temperature related fault/warning |
| 7Eh | STATUS_CML | - | R | 1 | Bit field | Returns the information of the module's communication related faults |
| 88h | READ_VIN | - | R | 2 | Linear | Returns the input voltage of the module |



NDQ900-48S12B-6LI Supported PMBus[™] Command list

| Command Code | Command Name | Default Value | Access Type | Data Bytes | Data Format | Description |
|-----------------|------------------------------|------------------|----------------|---------------|-------------|---|
| 8Bh | READ_VOUT | - | R | 2 | VOUT linear | Returns the output voltage of the module |
| 8Ch | READ_IOUT | - | R | 2 | Linear | Returns the output current of the module |
| 8Dh | READ_TEMP1 | - | R | 2 | Linear | Returns the module's temperature sensor temperature |
| 98h | PMBus_REVISION | - | R | 1 | Bit field | Read the version of the PMBus |
| 99h | PMBus_CMD_MFR_ID | - | R | Variable | Char | Artesyn |
| 9Ah | PMBus_CMD_MFR_MODEL | - | R | Variable | Char | Returns the name of the module |
| 9Bh | MFR_FW_REV | - | R | Variable | Char | Returns the version of the software |
| 9Ch | MFR_MOD_DATE_LOC_SN | - | R/W | Variable | Char | Returns the production's place of the module |
| 9Eh | PMBus_CMD_MFR_SERIAL | - | R/W | Variable | Char | Returns the serial number of the module |
| B6h | CLEAR BLACKBOX | - | W | 1 | N/A | Clear blackbox, set all history event data to 0 |
| DFh | BLACKBOX_EN | 01h | R/W | 1 | Bit field | Enable or disable the blackbox overwrite function |
| E0h | READ_HISTORY EVENTS | - | R | Variable | NA | Max 20 events, 20 commands |
| E1h | SET_HISTORY_EVENT _OFFSET | - | R/W | 1 | NA | Max 20 events, 20 commands |

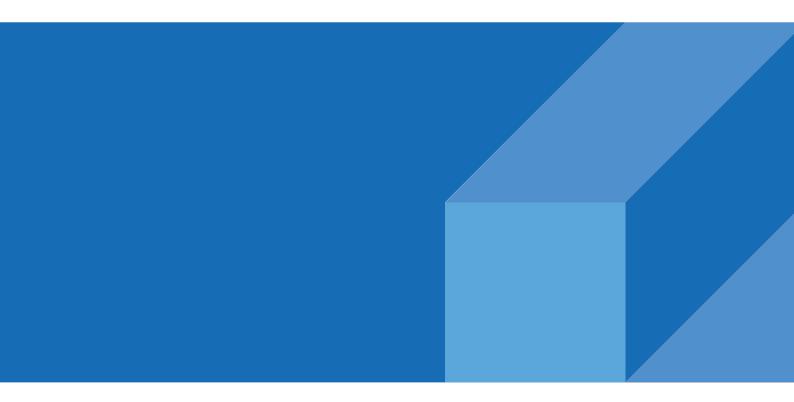


NDQ900-48S12B

RECORD OF REVISION AND CHANGES

| Issue | Date | Description | Originators |
|-------|------------|-------------|-------------|
| 1.0 | 10.21.2022 | First Issue | E. Wang |





ABOUT ADVANCED ENERGY

Advanced Energy (AE) has devoted more than three decades to perfecting power for its global customers. AE designs and manufactures highly engineered, precision power conversion, measurement and control solutions for mission-critical applications and processes.

Our products enable customer innovation in complex applications for a wide range of industries including semiconductor equipment, industrial, manufacturing, telecommunications, data center computing, and medical. With deep applications know-how and responsive service and support across the globe, we build collaborative partnerships to meet rapid technological developments, propel growth for our customers, and innovate the future of power.

PRECISION | POWER | PERFORMANCE | TRUST



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powersales@aei.com (Sales Support) productsupport.ep@aei.com (Technical Support) +1 888 412 7832 Specifications are subject to change without notice. Not responsible for errors or omissions. ©2020 Advanced Energy Industries, Inc. All rights reserved. Advanced Energy®, and AE® are U.S. trademarks of Advanced Energy Industries, Inc.